

Stabilized Structure from Motion without Disparity Induces Disparity Adaptation

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Summary

3D structures can be perceived based on the patterns of 2D motion signals [1, 2]. With orthographic projection of a 3D stimulus onto a 2D plane, the kinetic information can give a vivid impression of depth, but the depth order is intrinsically ambiguous, resulting in bistable or even multistable interpretations [3]. For example, an orthographic projection of dots on the surface of a rotating cylinder is perceived as a rotating cylinder with ambiguous direction of rotation [4]. We show that the bistable rotation can be stabilized by adding information, not to the dots themselves, but to their spatial context. More interestingly, the stabilized bistable motion can generate consistent rotation aftereffects. The rotation aftereffect can only be observed when the adapting and test stimuli are presented at the same stereo depth and the same retinal location, and it is not due to attentional tracking. The observed rotation aftereffect is likely due to direction-contingent disparity adaptation, implying that stimuli with kinetic depth may have activated neurons sensitive to different disparities, even though the stimuli have zero relative disparity. Stereo depth and kinetic depth may be supported by a common neural mechanism at an early stage in the visual system.

Results and Discussion

stimulus could almost completely stabilize the ambiguous stimuli.

The stimulus used in our study is a typical rotating cylinder generated from an orthographic projection of dots on a rotating 3D cylinder and is similar to stimuli used in previous psychophysical [3, 7] and physiological [4, 15, 16] studies. The ambiguous stimulus, perceived as a rotating cylinder with its rotation direction switching every few seconds, was presented to only one eye, (Figure 1A). (The percepts of two concave or convex sheets, moving across each other, are also possible [3] but were rarely seen by our observers; hence, they are not discussed in this paper and not depicted in figures.) When disparity information was added to the two ends of this bistable cylinder (i.e., a whole cylinder was presented to one eye, and only two ends of the cylinder were presented to the other eye), the whole cylinder was perceived to rotate in the direction specified by the disparity in the two ends, although the middle section contained no information to specify the depth order (Figure 1B). For the four observers tested, all perceived the cylinder as rotating unambiguously, 100% of the time, over multiple 1 min test periods. The spatial contextual cue was very effective in disambiguating the ambiguous motion.

Our observation differs from earlier reports of contextual biases on ambiguous rotation. The contextual bias due to simple 2D motion contrast simply enhances the opposite direction of motion in the central region and thus biases dots moving in such a direction to be perceived as being in front [12]. In the case of linkage between multiple bistable stimuli, the coupling tends to break down between unambiguous and ambiguous stimuli [11]. The key reason that the ambiguous and unambiguous sections in our stimulus remain strongly linked is that monocular presentation of the ambiguous

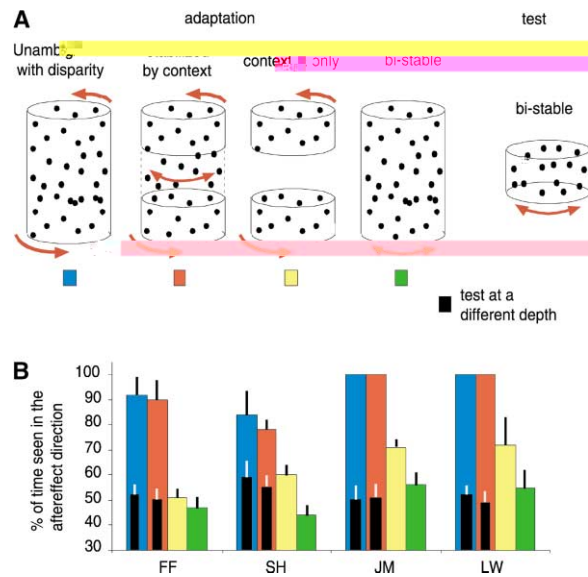


Figure 2. Effects of Adaptation to the Rotating Cylinders, including the Context-Stabilized Ambiguous Stimulus

(A) Four different adaptation stimuli were used. The test stimulus was an ambiguous cylinder. For the first two adaptation conditions, the test stimulus was placed at the same, as well as a different, stereo depth from the adaptation stimuli.

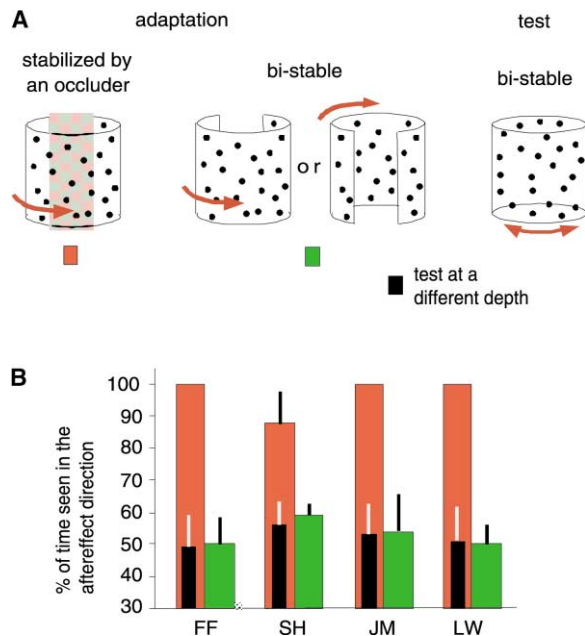


Figure 3. Effects of Adaptation to the Rotating Cylinder Stabilized by the Occlusion Cue

(A) The two adaptation stimuli had the same 2D motion signal. The stimulus with the explicit occluder was stabilized, whereas the one with the implicit occluder remained bistable, which served as a nice control condition. For the stabilized adaptation condition, the test stimulus was placed at the same, as well as a different, stereo depth from the adaptation stimulus.

(B) The aftereffect in the physical-occluder condition is significantly larger than that in the control condition, in which the 2D motion was the same but the 3D interpretation was bistable ($p < 0.01$). The aftereffect also required that the adapting and test patterns be placed on the same depth plane (black bars). Error bars denote 1 standard deviation.

testing period. In addition to the two stabilized rotation stimuli included as adaptors (full disparity unambiguous, context-stabilized, ambiguous), two control conditions were also included. In one control (context only), observers adapted to the two end units alone, without the middle ambiguous section. This was to test whether the aftereffect could simply be a spreading of adaptation from adjacent regions as a result of, for example, large receptive fields of the underlying neurons. Another control condition (bistable) was simply the extended bistable cylinder. This was to test whether merely being exposed to a bistable rotating cylinder for 1 min would lead to some stabilization during the test phase. After adaptation in both control conditions, observers perceived the testing cylinder as a bistable one, alternatively rotating in either direction with close to 50% chance (Figure 2B). When adapted to the two end units alone, the two naive observers (J.M. and L.W.) showed a weak aftereffect, likely due to less stable fixation during adaptation. However, the small aftereffect is much weaker than that generated by the stabilized, ambiguous adaptor.

When the ambiguous cylinder was stabilized with an occluder, the adaptation effect was also very strong (Figure 3). Three of the four observers always perceived

the test stimulus to be rotating in the direction opposite the adapted direction. Observer S.H. was the only one who saw occasional reversals in rotation direction during adaptation and, consequently, showed a slightly weaker adaptation effect (test stimulus rotating in the aftereffect direction 88% instead of 100% of the time). For a control condition, we took advantage of the observation that when the occluder was not explicitly depicted (subjective occluder), perception was not stable, but alternated between the two interpretations of depth (see Figure 1C). The 2D motion in the control condition was the same as motion with the explicit occluder. However, after adaptation to the control stimulus for 2 min, none of the observers showed any evidence of an aftereffect (Figure 3B). Note that, in both the test and the control condition, there was only one direction of motion signal in the middle section, which could and did lead to a simple 2D motion aftereffect. However, the simple 2D motion aftereffect could not influence the assignment of dots to the front or the back surface of the ambiguous test cylinder, as demonstrated by the absence of a rotation aftereffect in the control condition (Figure 3).

The Aftereffect Is Retinotopic and Disparity Specific

The adaptation effect found here is retinotopically specific. It requires that the test pattern be presented at the same retinal location as the adapting pattern [21, 22]. This retinotopic specificity is evident after adaptation to a rotating cylinder that has been disambiguated by disparity or stabilized by context or occluder. For example, in Figure 2, the context-only condition did not generate the adaptation effect. In further tests, the aftereffect was not observed as long as there was no spatial overlap between the adapting and testing stimuli. More surprisingly, this adaptation effect also requires that the test pattern be placed at the same stereo depth plane as the adapting pattern. The aftereffect disappeared if the adapting and test stimuli were presented with different absolute disparities (Figure 4A). Under such conditions, all observers perceived that the test pattern alternated direction of rotation, with each direction being observed for nearly the same amount of time (black bars in Figures 2 and 3). The retinotopic and disparity specificity of this aftereffect implies that this adaptation occurs relatively early in the visual system when one considers that rotation-sensitive neurons have quite large receptive fields [23]. It is interesting to note that the stabilization of rotation direction, over intermittent presentations [13, 14], seems to be somewhat retinotopic specific but not disparity specific [24].

The aftereffect could originate in mechanisms encoding depth together with translational motion. Alternatively, the aftereffect could be a rotation aftereffect [19]. In the latter case, because the aftereffect was observed only when the test stimuli and adapting stimuli were presented at the same disparity and location, our data suggest that, at the same retinal location, there are separate rotation-sensitive neurons of different disparities. This requirement makes the rotation adaptation model less parsimonious, although theoretically possible. How-

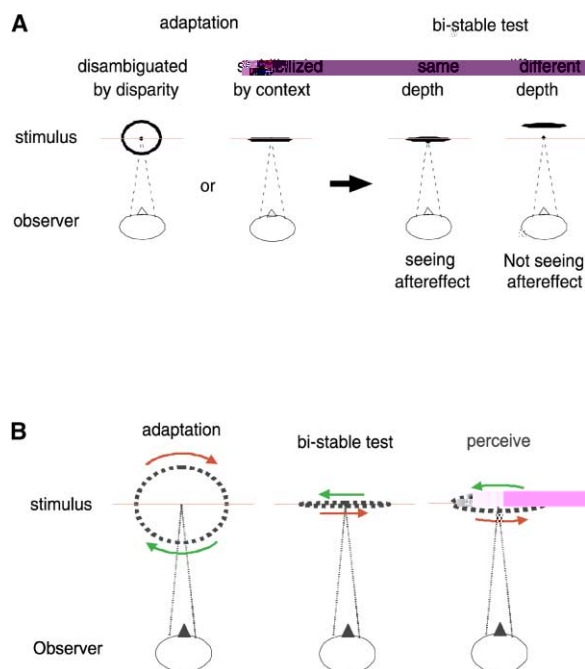


Figure 4. Adaptation Is Depth (Disparity) Specific

(A) The aftereffect was only observed when the test pattern was placed at the same depth plane as the adapting pattern. This was true for both the unambiguous adapting stimulus with disparity and the context-stabilized adapting stimulus.

(B) Illustration of motion direction contingent disparity aftereffect. During adaptation to a cylinder that is rotating clockwise, the dots moving to the left and to the right have different disparities (near and far, or crossed and uncrossed). When tests include moving dots with zero relative disparity (bistable), the leftward-moving dots are pushed away from the observer (green arrows), whereas the rightward-moving dots are pushed closer to the observer (red arrows). As a result, the test pattern is seen as rotating counterclockwise. Note that this aftereffect depends on the existence of different disparities associated with the two motion directions during adaptation.

ever, additional considerations argue against this model. First, an opponent mechanism tuned to rotation would predict that after prolonged adaptation to an unambiguous rotation, one would perceive a static cylinder to rotate in the opposite direction. However, this is not the case [7]. We failed to observe a rotation aftereffect with a static test pattern. Second, neurons responsible for complex motion perception show a large degree of position and scale invariance [23, 25], but, here, the aftereffect observed was quite specific in location and size. Third, the aftereffect is not tied to the structure of the adapting [21, 22] or testing stimulus. We observed that, after adaptation to the stabilized rotating cylinder, two flat sheets of oppositely moving dots with zero relative disparity showed a depth order consistent with the prediction of the disparity adaptation contingent on motion direction.

We favor the interpretation that the aftereffect is a motion direction-contingent disparity aftereffect, similar to that proposed by Nawrot and Blake [7] (see Figure 4B). However, the key difference between our results and the results of Nawrot and Blake is that Nawrot and

Blake found nonzero relative disparity between the two sets of dots moving in opposite directions, whereas in our experiment the two sets of dots had zero relative disparity. In other words, we believe that the kinetic depth adapted disparity-sensitive neurons as if they had nonzero relative disparities. This interpretation implies that, within certain limits, kinetic depth indeed is equivalent to the disparity depth in the sense that the disparity-tuned neurons are selectively responsive to depth signals defined by motion. Nawrot and Blake (1993) showed that disparity and kinetic depth could be perceptually metameric [22]. Here, our experiments suggest that the two mechanisms can cross-adapt, which is a stronger indication that the two have shared neural mechanisms.

In 2D motion, attentional tracking can induce a motion aftereffect when tested with a dynamic or flicker stimulus [26]. Attention was also shown to modulate the adaptation to 3D rotation [27]. Can attentional tracking account for our observation? We tested this possibility by reducing the number of dots in the disparity-defined, unambiguous rotating cylinder while preserving the perception of a rotating cylinder. The logic is that the attention system tracks the direction of rotation, whether there are 600 or 30 dots, but a system that depends on the energy of the motion and disparity signal would be much less stimulated by the 30 dots than the 600 dots. If the aftereffect were due to attentional tracking, then we would expect that tracking 30 dots should also generate an aftereffect. However, we failed to observe an aftereffect when we reduced the number of dots, suggesting that the aftereffect was not due to attentional tracking.

Conclusions

Contextual and pictorial information can disambiguate and stabilize an ambiguous kinetic stimulus. The stabilized ambiguous motion can generate a consistent aftereffect. The aftereffect observed is likely to be a motion direction-contingent disparity aftereffect, originated from the neuronal equivalence between disparity and motion parallax.

Experimental Procedures

Observers

Two experienced observers (F.F. and S.H.) and two naïve observers (W.L. and J.M.), with normal or corrected-to-normal vision, participated in these experiments. No formal stereo vision tests were given to the observers, but all observers could perceive random dot stereograms.

Apparatus and Stimuli

The stimuli were presented stereoscopically with liquid-crystal (LCD) shuttered glasses (StereoGraphics Corporation, San Rafael, CA). The moving dots were generated on a PC and presented on a SONY Trinitron Multiscan G420 19 inch monitor, with a spatial resolution of 1280×1024 pixels and a refresh rate of 100 Hz. During the experiments, observers wore the LCD glasses with the viewing distance set at 57 cm. The basic stimulus used in the experiments was a rotating cylinder defined with 600 small, randomly spaced dots ($0.08^\circ \times 0.08^\circ$). The speed of each dot followed a sine wave function. The 2D projection of the cylinder subtended 5 degrees vertically and 4 degrees horizontally. The dots were white (82.1 cm/m^2) against a black background. For conditions in which the cylinder motion was disambiguated by the disparity, disparity varied smoothly (within the limits of pixel size) from zero disparity at the

edge to $+0.1$ (or -0.1) degree of arc disparity at the center. The cylinder rotated at 0.231 revolutions/s.

In the first adaptation experiment (Figure 2), four kinds of adapting stimuli were used. They were (1) a rotating cylinder with complete, unambiguous disparity information; (2) a rotating cylinder with unambiguous disparity information at its two ends (i.e., the middle section of one eye's stimulus was removed from condition 1 to generate condition 2. The two ends were each 1.5° tall, and the middle section was 2° tall); (3) the two ends of a rotating cylinder with unambiguous disparity information (i.e., the middle sections of both eyes' stimuli were removed from condition 1 to generate condition 3; (4) a bistable rotating cylinder. The two eyes' stimuli were identical in this condition. The test stimulus was a bistable, rotating cylinder extending only 2° vertically; thus, the test stimulus was only presented in the location of the middle section of the adapting stimuli. Under conditions 1 and 2, the bistable test stimulus was also placed either at the same or different depth plane (0.2 deg disparity for all dots) as the adapting stimuli.

In the second adaptation experiment (Figure 3), there were two kinds of adapting stimuli. (1) A rotating cylinder (its parameters were the same as that in the first experiment) with a checkered red/green rectangle placed behind the front surface and blocking a vertical section of the back surface. The rectangle subtended 6.2° vertically and 2.8 degrees horizontally. Possible afterimages were avoided by the checker colors switching every 6 s. (2) A vertical section of the dots moving in one direction was removed (i.e., the rectangles in condition 1 were changed to the background color). The test stimulus was a bistable cylinder extending 5° vertically. Under condition 1, the test stimulus was presented in either the same depth plane as the adapting stimulus or at a different depth plane (0.2° disparity for all dots).

During the adaptation and test period, a fixation point was placed in both the center of the adapting stimulus and the center of the testing stimulus, both at the center of the monitor.

Testing Procedures

Observers adapted one of the adapting stimuli for 60 s (experiment 1) or 120 s (experiment 2) while maintaining fixation. This was followed by a 15 s test presentation of the bistable test stimulus. Observers pressed one of two keys to indicate the perceived rotation direction. They took breaks of at least 3 min between trials to avoid any carryover adaptation effects. The rotating direction of the adaptor and sequence of experimental conditions were randomized. Each observer ran six trials for every experimental condition, over multiple days. In other words, each bar in Figures 2 and 3 is the average of six independent measurements.

Acknowledgments

We thank Marty Banks and Dan Kersten for their useful discussions on the experimental design. We also thank Patricia Costello and Don MacLeod for their comments on an earlier draft of the paper. This research is supported in part by an award from the James S. McDonnell foundation.

Received: October 21, 2003

Revised: December 10, 2003

Accepted: December 22, 2003

Published: February 3, 2004

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